

# **Technical data sheet**

## GMX24-MFT-T

Customizable Non Fail-Safe multifunction technology actuator for controlling dampers in typical commercial HVAC applications.

- Torque motor 360 in-lb [40 Nm]
- Nominal voltage AC/DC 24 V
- Control MFT/programmable
- Position feedback 2...10 V





## Technical data

Nominal voltage frequency	50/60 Hz
Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V
Power consumption in operation	4.5 W
Power consumption in rest position	1.5 W
Transformer sizing	7 VA
Electrical Connection	Screw terminal (for 26 to 14 GA wire)
Overload Protection	electronic throughout 095° rotation
Torque motor	360 in-lb [40 Nm]
Input impedance	100 k $\Omega$ for 210 V (0.1 mA), 500 $\Omega$ for 420 mA
Position feedback U	210 V
Position feedback U note	Max. 0.5 mA
Position feedback U variable	VDC variable
Direction of motion motor	selectable with switch 0/1
Manual override	external push button
Angle of rotation	Max. 95°
Angle of rotation note	adjustable with mechanical stop
Running Time (Motor)	150 s / 90°
Running time motor note	constant, independent of load
Running time motor variable	75300 s
Noise level, motor	45 dB(A)
Position indication	reflective visual indicator (snap on)
Power source UL	Class 2 Supply
Degree of protection IEC/EN	IP20
Degree of protection NEMA/UL	NEMA 1
Enclosure	UL Enclosure Type 1
Agency Listing	cULus acc. to UL60730-1A/-2-14, CAN/CSA
	E60730-1:02
	CE acc. to 2014/30/EU and 2014/35/EU
	ISO 9001
UL 2043 Compliant	Suitable for use in air plenums per Section 300.22(C) of the NEC and Section 602 of the IMC
Ambient humidity	Max. 95% RH, non-condensing
	-22122°F [-3050°C]
· · ·	-40176°F [-4080°C]
Servicing	maintenance-free
Weight	2.7 lb [1.2 kg]
	Power consumption in operationPower consumption in rest positionTransformer sizingElectrical ConnectionOverload ProtectionTorque motorInput impedancePosition feedback UPosition feedback U notePosition feedback U variableDirection of motion motorManual overrideAngle of rotationAngle of rotation noteRunning time motor noteRunning time motor variableNoise level, motorPosition indicationPower source ULDegree of protection IEC/ENDegree of protection NEMA/ULEnclosureAgency ListingQuality StandardUL 2043 CompliantAmbient humidityAmbient temperatureStorage temperatureServicing



Footnotes	†Rated Impulse Voltage 800V, Type action 1, Control Pollution Degree 3.
Product features	
Application	For modulation of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. The actuator is mounted directly to a damper shaft up to 1.05" in diameter by means of its universal clamp. The default parameters for 210 V applications of theMFT actuator are assigned during manufacturing. If necessary, custom versions of the actuators can be ordered. The parameters can be changed by two means: pre- set and custom configurations from Belimo or on-site configurations using the Belimo PC-Tool software.
Operation	The actuator is not provided with and does not require any limit switches, but is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement.
	The GMB(X) series provides 95° of rotation and a visual indicator indicates position of the actuator. When reaching the damper or actuator end position, the actuator automatically stops. The gears can be manually disengaged with a button on the actuator cover.
	The GMB(X)24-MFT actuators use a brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in holding mode.
	Add-on auxiliary switches or feedback potentiometers are easily fastened directly onto the actuator body for signaling and switching functions.
Typical specification	Modulating control damper actuators shall be electronic direct coupled type, which require no crank arm and linkage and be capable of direct mounting to a shaft up to $1.05''$ diameter. Actuators must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a 500 $\Omega$ resistor, a 4 to 20 mA control input from an electronic controller or positioner. Actuators shall have brushless DC motor technology and be protected from overload at all angles of rotation. Actuators shall have reversing switch and manual override on the cover. Run time shall be constant and independent of torque. Actuators shall be cULus listed, have a 5-year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

#### Accessories

Electrical accessories	Description	Туре
	DC Voltage Input Rescaling Module	IRM-100
	Battery backup system, for non-spring return models	NSV24 US
	Battery, 12 V, 1.2 Ah (two required)	NSV-BAT
	Feedback potentiometer 10 k $\Omega$ add-on, grey	P10000A GR
	Feedback potentiometer 140 $\Omega$ add-on, grey	P140A GR
	Feedback potentiometer 2.8 k $\Omega$ add-on, grey	P2800A GR
	Feedback potentiometer 5 k $\Omega$ add-on, grey	P5000A GR
	Feedback potentiometer 500 $\Omega$ add-on, grey	P500A GR
	Signal simulator, Power supply AC 120 V	PS-100
	Convert Pulse Width Modulated Signal to a 210 V Signal for Belimo	PTA-250
	Proportional Actuators	
	Auxiliary switch 1 x SPDT add-on	S1A
	Auxiliary switch 2 x SPDT add-on	S2A
	Positioner for wall mounting	SGA24
	Cable conduit connector 1/2"	TF-CC US
	Gateway MP to LonWorks	UK24LON
	Resistor, 500 $\Omega$ , 1/4" wire resistor with 6" pigtail wires	ZG-R01
	Resistor kit, 50% voltage divider	ZG-R02
	Resistor kit, for -MFT95 actuator in 0135 $\Omega$ control application	ZG-R03
	Transformer, AC 120 V to AC 24 V, 40 VA	ZG-X40
	Feedback potentiometer 1 k $\Omega$ add-on, grey	P1000A GR



**Technical data sheet** 

echanical accessories	Description	Туре
	Actuator arm for standard shaft clamp	AH-GMA
	Shaft extension 240 mm ø20 mm for damper shaft ø822.7 mm	AV8-25
	Ball joint suitable for damper crank arm KH8, Multipack 10 pcs.	KG8
	Standard GK/GM clamp (1/2" to 1.05").	K-GM20
	Push rod for KG10A ball joint 36" L, 3/8" diameter	SH10
	Push rod for KG6 & KG8 ball joints (36" L, 5/16" diameter).	SH8
	Wrench 0.512 in. [13 mm]	TOOL-07
	Mounting bracket for AF	ZG-100
	Mounting bracket	ZG-101
	Dual actuator mounting bracket.	ZG-102
	Mounting bracket	ZG-103
	Mounting bracket	ZG-104
	Mounting bracket	ZG-109
	Linkage kit	ZG-110
	Damper clip for damper blade, 3.5" width.	ZG-DC1
	Damper clip for damper blade, 6" width.	ZG-DC2
	Mounting kit for linkage operation for flat installation	ZG-GMA
	Base plate extension for GMA to GM	Z-GMA
	Weather shield 13x8x6" [330x203x152 mm] (LxWxH)	ZS-100
	Base plate, for ZS-100	ZS-101
	Weather shield 406x213x102 mm [16x8-3/8x4"] (LxWxH)	ZS-150
	Explosion proof housing 16x10x6.435" [406x254x164 mm] (LxWxH), UL and CSA, Class I, Zone 1&2, Groups B, C, D, (NEMA 7), Class III, Hazardous (classified) Locations	ZS-260
	Weather shield 17-1/4x8-3/4x5-1/2" [438x222x140 mm] (LxWxH), NEMA 4X, with mounting brackets	ZS-300
	Weather shield 17-1/4x8-3/4x5-1/2" [438x222x140 mm] (LxWxH), NEMA 4X, with mounting brackets	ZS-300-5
	Shaft extension 1/2"	ZS-300-C1
	Shaft extension 3/4"	ZS-300-C2
	Shaft extension 1"	ZS-300-C3
Tools	Description	Туре
	Connecting cable 16 ft [5 m], A: RJ11 6/4 ZTH EU, B: 6-pin for connection to service socket	ZK1-GEN
	Connecting cable 16 ft [5 m], A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal	ZK2-GEN
	Connecting cable 16 ft [5 m], A+B: RJ12 6/6	ZK6-GEN
	Service Tool, with ZIP-USB function, for programmable and communicative Belimo actuators, VAV controller and HVAC performance devices	ZTH US

#### **Electrical installation**



A Provide overload protection and disconnect as required.

Actuators may also be powered by DC 24 V.

🔊 Only connect common to negative (-) leg of control circuits.

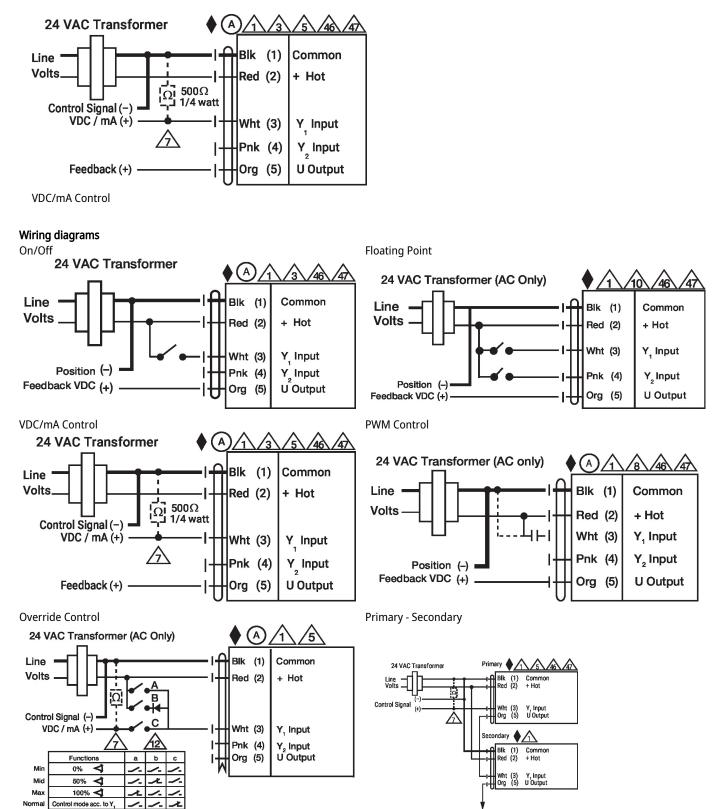
- A 500 Ω resistor (ZG-R01) converts the 4...20 mA control signal to 2...10 V.
- Control signal may be pulsed from either the Hot (Source) or Common (Sink) 24 V line.
- For triac sink the Common connection from the actuator must be connected to the Hot connection of the controller. Position feedback cannot be used with a triac sink controller; the actuator internal common reference is not compatible.



- \Lambda IN4004 or IN4007 diode. (IN4007 supplied, Belimo part number 40155).
- Actuators may be controlled in parallel. Current draw and input impedance must be observed.

A Master-Slave wiring required for piggy-back applications. Feedback from Master to control input(s) of Slave(s).







Ø 1/2" to 1.05" [12.7 to 26.67]

2/5" to 1.05" [10 to 26.67]

