

Cloud capable and communicating Non Fail-Safe damper actuator for controlling dampers in typical commercial HVAC applications.

- Torque motor 5 Nm
- Nominal voltage AC/DC 24 V

• Control modulating, communicative, Hybrid, Cloud

Conversion of sensor signals

• Ethernet 10/100 Mbit/s, TCP/IP, integrated web server

Communication via BACnet IP, Modbus TCP and Cloud



**Technical data sheet** 



## Technical data

Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.228.8 V / DC 21.626.4 V
	Power consumption in operation	3 W
	Power consumption in rest position	3 W
	Transformer sizing	4.5 VA
	Electrical Connection	18 GA appliance cable, 1/2" conduit connector and RJ45 socket (ethernet)
	Overload Protection	electronic throughout 095° rotation
Data bus communication	Communicative control	Cloud B&Cnet IP
		Modbus TCP
	Number of nodes	BACnet / Modbus see interface description
Functional data	Torque motor	5 Nm
	Operating range Y	210 V
	Operating range Y note	Hybrid via 210 V
	Operating range Y variable	0.510 V
	Position accuracy	±5%
	Direction of motion motor	selectable with switch 0/1
	Manual override	external push button
	Angle of rotation	95°
	Angle of rotation note	adjustable with mechanical stop
	Running Time (Motor)	150 s / 95°
	Running time motor variable	70220 s
	Adaptation Setting Range	manual
	Noise level, motor	35 dB(A)
	Mechanical interface	Universal shaft clamp 620 mm
	Position indication	Mechanical, 3065 mm stroke
Safety data	Protection class IEC/EN	III, Safety Extra-Low Voltage (SELV)
	Power source UL	Class 2 Supply
	Degree of protection IEC/EN	IP54
	Degree of protection NEMA/UL	NEMA 1
	Enclosure	UL Enclosure Type 1
	EMC	CE according to 2014/30/EU



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Safety data	Agency Listing	cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02 CE acc. to 2014/30/EU and 2014/35/EU
	Quality Standard	ISO 9001
	UL 2043 Compliant	Suitable for use in air plenums per Section 300.22(C) of the NEC and Section 602 of the IMC
	Type of action	Туре 1
	Ambient humidity	Max. 95% RH, non-condensing
	Ambient temperature	-22122°F [-3050°C]
	Storage temperature	-40176°F [-4080°C]
	Servicing	maintenance-free
Weight	Weight	1.5 lb [0.68 kg]
Materials	Housing material	UL94-5VA

#### **Product features**

Converter for sensors	Connection option for two sensors (passive sensor, active sensor or switching contact). The actuator serves as an analog/digital converter for the transmission of the sensor signal to the higher level system.
Communication	The configuration can be carried out through the integrated web server (RJ45 connection to the web browser), by communicative means or via the Cloud.
	Additional information regarding the integrated web server can be found in the separate documentation.
Control signal inversion	This can be inverted in cases of control with an analogue control signal. The inversion causes the reversal of the standard behavior, i.e. for control signal 0%, the actuator is opened to max and for control signal 100%, the actuator is closed.
Simple direct mounting	Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an anti- rotation device to prevent the actuator from revolving.
Data recording	The recorded data (integrated data recording for 13 months) can be used for analytical purposes.
	Download csv files via web browser.
Manual override	Manual override with push-button possible (the gear train is disengaged for as long as the button is pressed or remains locked).
Adjustable angle of rotation	Adjustable angle of rotation with mechanical end stops.
High functional reliability	The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.
Home position	The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out an adaptation, which is when the operating range and position feedback adjust themselves to the mechanical setting range.
	The actuator then moves into the position defined by the control signal.
	0% ccw. 0% ccw.

Adaptation and synchronisation

An adaption can be triggered manually by pressing the "Adaption" button. Both mechanical end stops are detected during adaption for setting the mechanical working range. The actuators operating range and runtime are scaled to this working range.

Technical data sheet



Electrical accessories	Description	Туре
	Positioner for front-panel mounting	SGF24
	Positioner for wall mounting	SGA24
	Resistor, 500 $\Omega$ , 1/4" wire resistor with 6" pigtail wires	ZG-R01
	Cable Gland	43442-00001
	(NEMA 4 models)	
	Cable conduit connector 1/2"	TF-CC US
	Transformer, AC 120 V to AC 24 V, 40 VA	ZG-X40
	Battery, 12 V, 1.2 Ah (two required)	NSV-BAT
	Battery backup system, for non-spring return models	NSV24 US
	Feedback potentiometer 15 k $\Omega$ gray	P15000A-F GR
	Feedback potentiometer 10 k $\Omega$ add-on, grey	P10000A GR
	Feedback potentiometer 5 k $\Omega$ add-on, grev	P5000A GR
	Feedback potentiometer 2.8 k $\Omega$ add-on, grev	P2800A GR
	Feedback potentiometer 1 kO add-on, grev	P1000A GR
	Feedback potentiometer 500 Q add-on grev	P500A GR
	Feedback potentiometer 140 Q add-on, grey	P140A GR
	Auviliary switch mercury-free	P475-1
	Auxiliary switch, mercury free	D175
	Auxiliary switch 2 x SDDT add on	F475
	Auxiliary switch 1 x SPDT add on	SZA S1A
Mechanical accessories		
Mechanical accessories		Туре
	Damper crank arm Slot width 6.2 mm, clamping range @1018 mm	KH6
	Damper crank arm Slot width 8.2 mm, clamping range Ø1018 mm	KH8
	Damper crank arm Slot width 8.2 mm, clamping range ø1425 mm	KH10
	Damper crank arm Slot width 8.2 mm, for ø1.05"	KH12
	Ball joint suitable for damper crank arm KH8, Multipack 10 pcs.	KG6
	Ball joint suitable for damper crank arm KH8, Multipack 10 pcs.	KG8
	Ball joint suitable for damper crank arm KH8 / KH10, Multipack 10 pcs.	KG10A
	Push rod for KG6 & KG8 ball joints (36" L, 5/16" diameter).	SH8
	Push rod for KG10A ball joint 36" L, 3/8" diameter	SH10
	Damper clip for damper blade, 3.5" width.	ZG-DC1
	Damper clip for damper blade, 6" width.	ZG-DC2
	Weather shield 13x8x6" [330x203x152 mm] (LxWxH)	ZS-100
	Base plate, for ZS-100	ZS-101
	Weather shield 406x213x102 mm [16x8-3/8x4"] (LxWxH)	ZS-150
	Shaft extension 240 mm ø20 mm for damper shaft ø822.7 mm	AV8-25
	Anti-rotation bracket TF/NKQ/AM/NM/LM.	TF-P
	Mounting bracket for AF	ZG-100
	Mounting bracket	ZG-101
	Wrench 0.32 in and 0.39 in [8 mm and 10 mm]	TOOL-06
	Adapter for auxiliary switch and feedback potentiometer	Z-SPA
	LMB(X) clamp (3/8")	K-LM10
	LMB(X) clamp (1/2").	K-LM12
	Standard LMB(X) clamp (5/8").	K-LM16
	LMB(X) clamp (3/4").	K-LM20
	Shaft extension for 1/2" diameter shafts (3" L).	ZG-LMSA
	Shaft extension for 3/8" diameter shafts (4"1)	7G-I MSA-1
	Shaft extension for 1/2" diameter shafts (5"1)	7G-I MSΔ-1/2-5
	Shaft extension 170 mm ø10 mm for damper shaft ø6 16 mm	
	Mounting plate for SGE	76-SGF
Tools	Description	
10015		-74C
	Signal simulator, Power supply AC 120 V	PS-100

## **Electrical installation**



Supply from isolating transformer.

Parallel connection of other actuators possible. Observe the performance data.



# Wiring diagrams



1 = black 2 = red 5 = orange 10 = yellow-black 11 = yellow-pink 12 = yellow-grey

Cable colors:

Web-Browser

Functions

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Connection of a notebook for parametrisation and manual

Optional connection via RJ45 (direct connection Notebook / connection via Intranet or Internet) for access to the

integrated web server

control via RJ45.

The connection diagrams shows connections for the first sensor on terminal S1, while the second sensor can be connected identically on terminal S2.

Parallel use of different sensor types is permitted.

For hybrid operation, S1 is used for the control signal Y and must be configured as an active sensor.

## **Functions with specific parameters (parametrization necessary)** TCP/IP (Cloud) / BACnet IP / Modbus TCP



TCP/IP (Cloud) / BACnet IP / Modbus TCP with analogue setpoint (hybrid operation)





## **Technical data sheet**

## Connection of passive sensors



## Switching contact connection



Connection of active sensors



## Dimensions

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