

Customizable Non Fail-Safe modulating actuator for controlling dampers in typical commercial HVAC applications.

- Torque motor 90 in-lb [10 Nm]
- Nominal voltage AC/DC 24 V
- Control Modulating
- Position feedback 2...10 V



**Technical data sheet** 



NMX24-SR-T

## Technical data

Electrical data	Nominal voltage	AC/DC 24 V	
	Nominal voltage frequency	50/60 Hz	
	Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V	
	Power consumption in operation	2.5 W	
	Power consumption in rest position	0.4 W	
	Transformer sizing	5 VA	
	Electrical Connection	Screw terminal (for 26 to 14 GA wire)	
	Overload Protection	electronic throughout 095° rotation	
Functional data	Torque motor	90 in-lb [10 Nm]	
	Operating range Y	210 V	
	Operating range Y note	420 mA w/ ZG-R01 (500 Ω, 1/4 W resistor)	
	Input impedance	100 kΩ (0.1 mA), 500 Ω	
	Position feedback U	210 V	
	Position feedback U note	Max. 0.5 mA	
	Direction of motion motor	selectable with switch 0/1	
	Manual override	external push button	
	Angle of rotation	Max. 95°	
	Angle of rotation note	adjustable with mechanical stop	
	Running Time (Motor)	95 s / 90°	
	Running time motor note	constant, independent of load	
	Noise level, motor	45 dB(A)	
	Position indication	reflective visual indicator (snap on)	
Safety data	Power source UL	Class 2 Supply	
	Degree of protection IEC/EN	IP20	
	Degree of protection NEMA/UL	NEMA 1	
	Enclosure	UL Enclosure Type 1	
	Agency Listing	cULus acc. to UL60730-1A/-2-14, CAN/CSA	
		E60730-1:02	
		CE acc. to 2014/30/EU and 2014/35/EU	
	Quality Standard	ISO 9001	
	UL 2043 Compliant	Suitable for use in air plenums per Section 300.22(C) of the NEC and Section 602 of the	
		IMC	
	Ambient humidity	Max. 95% RH, non-condensing	
	Ambient temperature	-22122°F [-3050°C]	
	Storage temperature	-40176°F [-4080°C]	
	Servicing	maintenance-free	
Weight	Weight	1.5 lb [0.68 kg]	
Materials	Housing material	UL94-5VA	



Product features		
Application	For proportional modulation of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications.	
	The actuator is mounted directly to a damper shaft up to 1.05" in diameter by means of its universal clamp, 1/2" self centered default. A crank arm and several mounting brackets are available for applications where the actuator cannot be direct coupled to the damper shaft.	
	The actuator operates in response to a 2 to 10 VDC, or with the addition of a 500 $\Omega$ resistor, a 4 to 20 mA control input from an electronic controller or positioner. A 2 to 10 VDC feedback signals provided for position indication or master-slave applications.	
Operation	The actuator is not provided with and does not require any limit switches, but is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement.	
	The NMB(X) series provides 95° of rotation and a visual indicator indicates position of the actuator. When reaching the damper or actuator end position, the actuator automatically stop The gears can be manually disengaged with a button on the actuator cover.	
	The NMB(X)24-SR actuators use a sensorless brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition.Power consumption is reduced in holding mode.	
	Add-on auxiliary switches or feedback potentiometers are easily fastened directly onto the actuator body for signaling and switching functions.	
Typical specification	Proportional control damper actuators shall be electronic direct-coupled type, which require no crank arm and linkage and be capable of direct mounting to a shaft up to 1.05" diameter. Actuators must provide proportional damper control in response to a 2 to 10 VDC or, with the addition of a 500 $\Omega$ resistor, a 4 to 20 mA control input from an electronic controller or positioner. Actuators shall have brushless DC motor technology and be protected from overload at all angles of rotation. Actuators shall have reversing switch and manual override on the cover. Actuator will be provided with screw terminal strip for electrical connections. Run time shall be constant and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position indication. Actuators shall be cULus listed, have a 5-year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.	

## Accessories

Electrical accessories	Description	Туре
	Battery backup system, for non-spring return models	NSV24 US
	Battery, 12 V, 1.2 Ah (two required)	NSV-BAT
	Auxiliary switch 1x SPDT add-on	S1A
	Auxiliary switch 2x SPDT add-on	S2A
	Feedback potentiometer 140 $\Omega$ add-on, grey	P140A GR
	Feedback potentiometer 1 k $\Omega$ add-on, grey	P1000A GR
	Feedback potentiometer 10 k $\Omega$ add-on, grey	P10000A GR
	Feedback potentiometer 2.8 k $\Omega$ add-on, grey	P2800A GR
	Feedback potentiometer 500 $\Omega$ add-on, grey	P500A GR
	Feedback potentiometer 5 k $\Omega$ add-on, grey	P5000A GR



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Mechanical accessories	Description	Туре
	Shaft clamp reversible, clamping range ø820 mm	K-NA
	Mounting bracket for AF	ZG-100
	Mounting bracket	ZG-101
	Dual actuator mounting bracket.	ZG-102
	Mounting bracket	ZG-103
	Mounting bracket	ZG-104
	Mounting kit for linkage operation for flat installation	ZG-NMA
	Shaft extension for 1/2" diameter shafts (3.8" L).	ZG-NMSA-1
	Weather shield 13x8x6" [330x203x152 mm] (LxWxH)	ZS-100
	Terminal-strip cover for NEMA 2 rating (-T models).	ZS-T
	Wrench 0.32 in and 0.39 in [8 mm and 10 mm]	TOOL-06
	Shaft extension 240 mm ø20 mm for damper shaft ø822.7 mm	AV8-25
	Weather shield 406x213x102 mm [16x8-3/8x4"] (LxWxH)	ZS-150
	Linkage kit	ZG-JSL
	Jackshaft Retrofit Linkage with Belimo Rotary Actuators	

## **Electrical installation**

A Provide overload protection and disconnect as required.

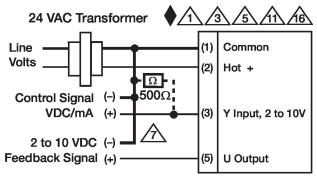
Actuators may also be powered by DC 24 V.

 $\overline{\underline{A}}$  Only connect common to negative (-) leg of control circuits.

A 500 Ω resistor (ZG-R01) converts the 4...20 mA control signal to 2...10 V.

Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.

 $\Lambda_{16}$  Actuators are provided with a numbered screw terminal strip instead of a cable.



2...10 V / 4...20 mA Control



